

CONTENTS

Introduction	xv
Notation	xvii
1 Simple Stress and Strain	1
1.1 <i>Load</i>	1
1.2 <i>Direct or normal stress (σ)</i>	2
1.3 <i>Direct strain (ε)</i>	2
1.4 <i>Sign convention for direct stress and strain</i>	2
1.5 <i>Elastic materials – Hooke's law</i>	3
1.6 <i>Modulus of elasticity – Young's modulus</i>	3
1.7 <i>Tensile test</i>	4
1.8 <i>Ductile materials</i>	8
1.9 <i>Brittle materials</i>	8
1.10 <i>Poisson's ratio</i>	9
1.11 <i>Application of Poisson's ratio to a two-dimensional stress system</i>	10
1.12 <i>Shear stress</i>	11
1.13 <i>Shear strain</i>	11
1.14 <i>Modulus of rigidity</i>	12
1.15 <i>Double shear</i>	12
1.16 <i>Allowable working stress – factor of safety</i>	12
1.17 <i>Load factor</i>	13
1.18 <i>Temperature stresses</i>	13
1.19 <i>Stress concentrations – stress concentration factor</i>	14
1.20 <i>Toughness</i>	14
1.21 <i>Creep and fatigue</i>	15
<i>Examples</i>	17
<i>Problems</i>	25
<i>Bibliography</i>	26
2 Compound Bars	27
<i>Summary</i>	27
2.1 <i>Compound bars subjected to external load</i>	28

2.2	<i>Compound bars – “equivalent” or “combined” modulus</i>	29
2.3	<i>Compound bars subjected to temperature change</i>	30
2.4	<i>Compound bar (tube and rod)</i>	32
2.5	<i>Compound bars subjected to external load and temperature effects</i>	34
2.6	<i>Compound thick cylinders subjected to temperature changes</i>	34
	<i>Examples</i>	34
	<i>Problems</i>	39
3	Shearing Force and Bending Moment Diagrams	41
	<i>Summary</i>	41
3.1	<i>Shearing force and bending moment</i>	41
3.1.1	<i>Shearing force (S.F.) sign convention</i>	42
3.1.2	<i>Bending moment (B.M.) sign convention</i>	42
3.2	<i>S.F. and B.M. diagrams for beams carrying concentrated loads only</i>	43
3.3	<i>S.F. and B.M. diagrams for uniformly distributed loads</i>	46
3.4	<i>S.F. and B.M. diagrams for combined concentrated and uniformly distributed loads</i>	47
3.5	<i>Points of contraflexure</i>	48
3.6	<i>Relationship between S.F. Q, B.M. M, and intensity of loading w</i>	49
3.7	<i>S.F. and B.M. diagrams for an applied couple or moment</i>	50
3.8	<i>S.F. and B.M. diagrams for inclined loads</i>	52
3.9	<i>Graphical construction of S.F. and B.M. diagrams</i>	54
3.10	<i>S.F. and B.M. diagrams for beams carrying distributed loads of increasing value</i>	55
3.11	<i>S.F. at points of application of concentrated loads</i>	55
	<i>Examples</i>	56
	<i>Problems</i>	59
4	Bending	62
	<i>Summary</i>	62
	<i>Introduction</i>	63
4.1	<i>Simple bending theory</i>	64
4.2	<i>Neutral axis</i>	66
4.3	<i>Section modulus</i>	68
4.4	<i>Second moment of area</i>	68
4.5	<i>Bending of composite or flitched beams</i>	70
4.6	<i>Reinforced concrete beams – simple tension reinforcement</i>	71
4.7	<i>Skew loading</i>	73
4.8	<i>Combined bending and direct stress – eccentric loading</i>	74

4.9	<i>“Middle-quarter” and “middle-third” rules</i>	76
4.10	<i>Shear stresses owing to bending</i>	77
4.11	<i>Strain energy in bending</i>	78
4.12	<i>Limitations of the simple bending theory</i>	78
	<i>Examples</i>	79
	<i>Problems</i>	88
5	Slope and Deflection of Beams	92
	<i>Summary</i>	92
	<i>Introduction</i>	94
5.1	<i>Relationship between loading, S.F., B.M., slope and deflection</i>	94
5.2	<i>Direct integration method</i>	97
5.3	<i>Macaulay’s method</i>	102
5.4	<i>Macaulay’s method for u.d.l’s</i>	105
5.5	<i>Macaulay’s method for beams with u.d.l. applied over part of the beam</i>	106
5.6	<i>Macaulay’s method for couple applied at a point</i>	106
5.7	<i>Mohr’s “area–moment” method</i>	108
5.8	<i>Principle of superposition</i>	112
5.9	<i>Energy method</i>	112
5.10	<i>Maxwell’s theorem of reciprocal displacements</i>	112
5.11	<i>Continuous beams – Clapeyron’s “three-moment” equation</i>	115
5.12	<i>Finite difference method</i>	118
5.13	<i>Deflections due to temperature effects</i>	119
	<i>Examples</i>	123
	<i>Problems</i>	138
6	Built-in Beams	140
	<i>Summary</i>	140
	<i>Introduction</i>	141
6.1	<i>Built-in beam carrying central concentrated load</i>	141
6.2	<i>Built-in beam carrying uniformly distributed load across the span</i>	142
6.3	<i>Built-in beam carrying concentrated load offset from the centre</i>	143
6.4	<i>Built-in beam carrying a non-uniform distributed load</i>	145
6.5	<i>Advantages and disadvantages of built-in beams</i>	146
6.6	<i>Effect of movement of supports</i>	146
	<i>Examples</i>	147
	<i>Problems</i>	152

7	Shear Stress Distribution	154
	<i>Summary</i>	154
	<i>Introduction</i>	155
	7.1 <i>Distribution of shear stress due to bending</i>	156
	7.2 <i>Application to rectangular sections</i>	157
	7.3 <i>Application to I-section beams</i>	158
	7.3.1 <i>Vertical shear in the web</i>	159
	7.3.2 <i>Vertical shear in the flanges</i>	159
	7.3.3 <i>Horizontal shear in the flanges</i>	160
	7.4 <i>Application to circular sections</i>	162
	7.5 <i>Limitation of shear stress distribution theory</i>	164
	7.6 <i>Shear centre</i>	165
	<i>Examples</i>	166
	<i>Problems</i>	173
8	Torsion	176
	<i>Summary</i>	176
	8.1 <i>Simple torsion theory</i>	177
	8.2 <i>Polar second moment of area</i>	179
	8.3 <i>Shear stress and shear strain in shafts</i>	180
	8.4 <i>Section modulus</i>	181
	8.5 <i>Torsional rigidity</i>	182
	8.6 <i>Torsion of hollow shafts</i>	182
	8.7 <i>Torsion of thin-walled tubes</i>	182
	8.8 <i>Composite shafts – series connection</i>	182
	8.9 <i>Composite shafts – parallel connection</i>	183
	8.10 <i>Principal stresses</i>	184
	8.11 <i>Strain energy in torsion</i>	184
	8.12 <i>Variation of data along shaft length – torsion of tapered shafts</i>	186
	8.13 <i>Power transmitted by shafts</i>	186
	8.14 <i>Combined stress systems – combined bending and torsion</i>	187
	8.15 <i>Combined bending and torsion – equivalent bending moment</i>	187
	8.16 <i>Combined bending and torsion – equivalent torque</i>	188
	8.17 <i>Combined bending, torsion and direct thrust</i>	189
	8.18 <i>Combined bending, torque and internal pressure</i>	189
	<i>Examples</i>	190
	<i>Problems</i>	195

9 Thin Cylinders and Shells	198
<i>Summary</i>	198
9.1 <i>Thin cylinders under internal pressure</i>	198
9.1.1 <i>Hoop or circumferential stress</i>	199
9.1.2 <i>Longitudinal stress</i>	199
9.1.3 <i>Changes in dimensions</i>	200
9.2 <i>Thin rotating ring or cylinder</i>	201
9.3 <i>Thin spherical shell under internal pressure</i>	202
9.3.1 <i>Change in internal volume</i>	203
9.4 <i>Vessels subjected to fluid pressure</i>	203
9.5 <i>Cylindrical vessel with hemispherical ends</i>	204
9.6 <i>Effects of end plates and joints</i>	205
9.7 <i>Wire-wound thin cylinders</i>	206
<i>Examples</i>	208
<i>Problems</i>	213
10 Thick cylinders	215
<i>Summary</i>	215
10.1 <i>Difference in treatment between thin and thick cylinders – basic assumptions</i>	216
10.2 <i>Development of the Lamé theory</i>	217
10.3 <i>Thick cylinder – internal pressure only</i>	219
10.4 <i>Longitudinal stress</i>	220
10.5 <i>Maximum shear stress</i>	221
10.6 <i>Change of cylinder dimensions</i>	221
10.7 <i>Comparison with thin cylinder theory</i>	222
10.8 <i>Graphical treatment – Lamé line</i>	223
10.9 <i>Compound cylinders</i>	224
10.10 <i>Compound cylinders – graphical treatment</i>	226
10.11 <i>Shrinkage or interference allowance</i>	226
10.12 <i>Hub on solid shaft</i>	229
10.13 <i>Force fits</i>	229
10.14 <i>Compound cylinder – different materials</i>	230
10.15 <i>Uniform heating of compound cylinders of different materials</i>	231
10.16 <i>Failure theories – yield criteria</i>	233
10.17 <i>Plastic yielding – “auto-frettage”</i>	233
10.18 <i>Wire-wound thick cylinders</i>	234
<i>Examples</i>	236
<i>Problems</i>	251

11	Strain Energy	254
	<i>Summary</i>	254
	<i>Introduction</i>	256
11.1	<i>Strain energy – tension or compression</i>	257
11.2	<i>Strain energy – shear</i>	259
11.3	<i>Strain energy – bending</i>	260
11.4	<i>Strain energy – torsion</i>	261
11.5	<i>Strain energy of a three-dimensional principal stress system</i>	262
11.6	<i>Volumetric or dilatational strain energy</i>	262
11.7	<i>Shear or distortional strain energy</i>	263
11.8	<i>Suddenly applied loads</i>	263
11.9	<i>Impact loads – axial load application</i>	264
11.10	<i>Impact loads – bending applications</i>	265
11.11	<i>Castigliano’s first theorem for deflection</i>	266
11.12	<i>“Unit-load” method</i>	268
11.13	<i>Application of Castigliano’s theorem to angular movements</i>	269
11.14	<i>Shear deflection</i>	269
	<i>Examples</i>	274
	<i>Problems</i>	292
12	Springs	297
	<i>Summary</i>	297
	<i>Introduction</i>	299
12.1	<i>Close-coiled helical spring subjected to axial load W</i>	299
12.2	<i>Close-coiled helical spring subjected to axial torque T</i>	300
12.3	<i>Open-coiled helical spring subjected to axial load W</i>	301
12.4	<i>Open-coiled helical spring subjected to axial torque T</i>	304
12.5	<i>Springs in series</i>	305
12.6	<i>Springs in parallel</i>	306
12.7	<i>Limitations of the simple theory</i>	306
12.8	<i>Extension springs – initial tension</i>	307
12.9	<i>Allowable stresses</i>	308
12.10	<i>Leaf or carriage spring: semi-elliptic</i>	309
12.11	<i>Leaf or carriage spring: quarter-elliptic</i>	312
12.12	<i>Spiral spring</i>	314
	<i>Examples</i>	316
	<i>Problems</i>	324

13	Complex Stresses	326
	<i>Summary</i>	326
13.1	<i>Stresses on oblique planes</i>	326
13.2	<i>Material subjected to pure shear</i>	327
13.3	<i>Material subjected to two mutually perpendicular direct stresses</i>	329
13.4	<i>Material subjected to combined direct and shear stresses</i>	329
13.5	<i>Principal plane inclination in terms of the associated principal stress</i>	331
13.6	<i>Graphical solution – Mohr’s stress circle</i>	332
13.7	<i>Alternative representations of stress distributions at a point</i>	334
13.8	<i>Three-dimensional stresses – graphical representation</i>	338
	<i>Examples</i>	342
	<i>Problems</i>	358
14	Complex Strain and the Elastic Constants	361
	<i>Summary</i>	361
14.1	<i>Linear strain for tri-axial stress state</i>	361
14.2	<i>Principal strains in terms of stresses</i>	362
14.3	<i>Principal stresses in terms of strains – two-dimensional stress system</i>	363
14.4	<i>Bulk modulus K</i>	363
14.5	<i>Volumetric strain</i>	363
14.6	<i>Volumetric strain for unequal stresses</i>	364
14.7	<i>Change in volume of circular bar</i>	365
14.8	<i>Effect of lateral restraint</i>	366
14.9	<i>Relationship between the elastic constants E, G, K and ν</i>	367
14.10	<i>Strains on an oblique plane</i>	370
14.11	<i>Principal strain – Mohr’s strain circle</i>	372
14.12	<i>Mohr’s strain circle – alternative derivation from the general stress equations</i>	374
14.13	<i>Relationship between Mohr’s stress and strain circles</i>	375
14.14	<i>Construction of strain circle from three known strains (McClintock method) – rosette analysis</i>	378
14.15	<i>Analytical determination of principal strains from rosette readings</i>	381
14.16	<i>Alternative representations of strain distributions at a point</i>	383
14.17	<i>Strain energy of three-dimensional stress system</i>	385
	<i>Examples</i>	387
	<i>Problems</i>	397
15	Theories of Elastic Failure	401
	<i>Summary</i>	401
	<i>Introduction</i>	401

15.1	<i>Maximum principal stress theory</i>	402
15.2	<i>Maximum shear stress theory</i>	403
15.3	<i>Maximum principal strain theory</i>	403
15.4	<i>Maximum total strain energy per unit volume theory</i>	403
15.5	<i>Maximum shear strain energy per unit volume (or distortion energy) theory</i>	403
15.6	<i>Mohr's modified shear stress theory for brittle materials</i>	404
15.7	<i>Graphical representation of failure theories for two-dimensional stress systems (one principal stress zero)</i>	406
15.8	<i>Graphical solution of two-dimensional theory of failure problems</i>	410
15.9	<i>Graphical representation of the failure theories for three-dimensional stress systems</i>	411
15.9.1	<i>Ductile materials</i>	411
15.9.2	<i>Brittle materials</i>	412
15.10	<i>Limitations of the failure theories</i>	413
15.11	<i>Effect of stress concentrations</i>	414
15.12	<i>Safety factors</i>	414
15.13	<i>Modes of failure</i>	416
	<i>Examples</i>	417
	<i>Problems</i>	427
16	Experimental Stress Analysis	430
	<i>Introduction</i>	430
16.1	<i>Brittle lacquers</i>	431
16.2	<i>Strain gauges</i>	435
16.3	<i>Unbalanced bridge circuit</i>	437
16.4	<i>Null balance or balanced bridge circuit</i>	437
16.5	<i>Gauge construction</i>	437
16.6	<i>Gauge selection</i>	438
16.7	<i>Temperature compensation</i>	439
16.8	<i>Installation procedure</i>	440
16.9	<i>Basic measurement systems</i>	441
16.10	<i>D.C. and A.C. systems</i>	443
16.11	<i>Other types of strain gauge</i>	444
16.12	<i>Photoelasticity</i>	445
16.13	<i>Plane-polarised light – basic polariscope arrangements</i>	446
16.14	<i>Temporary birefringence</i>	446
16.15	<i>Production of fringe patterns</i>	448
16.16	<i>Interpretation of fringe patterns</i>	449
16.17	<i>Calibration</i>	450

16.18	<i>Fractional fringe order determination – compensation techniques</i>	451
16.19	<i>Isoclinics – circular polarisation</i>	452
16.20	<i>Stress separation procedures</i>	454
16.21	<i>Three-dimensional photoelasticity</i>	454
16.22	<i>Reflective coating technique</i>	454
16.23	<i>Other methods of strain measurement</i>	456
	<i>Bibliography</i>	456
Appendix 1.	Typical mechanical and physical properties for engineering materials	xxi
Appendix 2.	Typical mechanical properties of non-metals	xxii
Appendix 3.	Other properties of non-metals	xxiii
Index		xxv